VEX Robotics Competition - Gateway

Robot Inspection Checklist (VEXnet or Crystal)

V8	=,	×
COMP		
GAT	EWA	Y

Te	eam Number:	GATEWAY		
S	ize Inspection			
	Robot fits within starting size restrictions (18" x 18" x 18") does not touch walls or ceiling of the sizing box! Robot should be measured WITH Robot Flag & Team ID # Plates installed.	t R4		
Overall Inspection				
	Team is only competing with ONE robot they have no spare or replacement robots.	R1		
	Robot displays VEX Team Identification Number on at least (2) opposing sides.	R18		
	Robot does NOT contain any components which will be intentionally detached on the playing-field.	G10		
	Robot does NOT contain any components that could damage the playing-field or other robots.	R3		
	Robot does NOT contain any sharp edges or corners.	R3		
	Robot poses NO obvious unnecessary risk of entanglement.	R3		
	Robot on/off switch is accessible & Microcontroller lights are visible without moving or lifting the robot.	R16		
	Robot Flag Holder is present and adequately holds the flag during normal robot operation.	R19		
	When installed the Robot Flag is non-functional and does not extend outside the sizing box.	R19ab		
VEX Parts Inspection				
	ALL Robot components are (or are IDENTICAL to) OFFICIAL VEX Products as sold on VEXrobotics.com	R5 R6		
	Robot does not VEX products not intended for use as a robot component or any VEX packaging.	R5b		
	ALL Components on the Robot NOT meeting VRC Inspection Criteria are NON-FUNCTIONAL decorations	R7d		
	Any grease is used only in moderation on components that do not contact the field, objects, or other robots.	R7e		
	Any polycarbonate on the robot was cut from a single sheet of 0.0625" material not larger than 12"x24".	R7f		
	Robot has only (1) VEX EDR Microcontroller (Cortex or PIC)	R9		
	Robot utilizes the VEXnet wireless communication system, or VEX 75 MHz Crystals when allowed	R10		
	None of the <i>electronics</i> are from the VEXplorer system.	R10b		
	Total number of Servos and Motors is not more than (10) and no more than four (4) are 2-wire #393 motors.	R11 R11a		
	Each 2-wire motor is plugged into its own 2-wire port or into a Model 29 motor controller	R11b		
	A motor may only be controlled by a single controller port	R11c		
	Robot uses a maximum of (1) Y-Cable per each 3-wire Motor Port (cannot "Y" off a 2-wire Motor Port)	R12		
	Robot uses (1) VEX 7.2V (Robot) Power Pack as the primary power source.	R13		
	If the Robot has a Power Expander, it has a 2nd 7.2V (Robot) Power Pack	R13		
	Robot uses a maximum of (1) VEX Power Expander	R13b		
	If Using VEXnet, Robot has a charged 9V Backup Battery connected	R13c		
	Robot is not controlled by more than (2) VEX hand-held transmitters.	R14		
	NO VEX electrical components have been modified from their original state.	R15a		
	NO Method of attachment NOT provided by the VEX Design System is used. (Welding, Gluing, etc.)	R15b		
	Any repairs done to the wires on a VEX component do not extend the length or enhance the functionality of the component. Repairs may be covered by 1" (2.54cm) of insulating tape or shrink wrap tubing.	R15c		
Field Control Check				
	Robot successfully completes the "Field Control Check" Procedure See Inspection Guidelines	R20		
	Robot enters Autonomous mode when prompted - with no driver control for duration of Autonomous	R20		
	The Hand-held Controller(s) ONLY control the robot when robot is in Driver mode	R20		
Pa	Pass / Fail: Inspector Initials: Team Initials:			